

SYSTEM & CONTROL (SKMM)

TARIKH	TAJUK
02A,08/07/2024,08.00-10.30,Random	Palm Fruit Ripeness Evaluation
02A,08/07/2024,08.00-10.30,Random	Low Cost Smart Nasogastric Feeding System
02A,08/07/2024,08.00-10.30,Random	VIRTUAL REALITY LABORATORY
02A,08/07/2024,08.00-10.30,Random	Mechatronic System to Assist Disable Driver
02A,08/07/2024,08.00-10.30,Random	Design and development of an passive exoskeleton for detachable CANTAS
02B,08/07/2024,10.30-13.00,Random	Micro Surveillance Drone
02B,08/07/2024,10.30-13.00,Random	Transportation to enter cavern
02B,08/07/2024,10.30-13.00,Random	Design and Development of a Magnet Repulsion Engine for Sustainable Energy Generation
02B,08/07/2024,10.30-13.00,Random	Solar powered outdoor air purifier/dust collector
02B,08/07/2024,10.30-13.00,Random	Assessing Power Generation Potential from Outdoor VRV Units
02B,08/07/2024,10.30-13.00,Random	Flywheel Energy Storage-FES
02C,08/07/2024,14.00-16.30,Random	Multiobjective optimization of Sensor/actuator placement on flexible beam structures
02C,08/07/2024,14.00-16.30,Random	Direct Active Vibration Control of Flexible Beam Structure
02C,08/07/2024,14.00-16.30,Random	Palm Tree Height and Position Detection
02C,08/07/2024,14.00-16.30,Random	Palm Oil Ripeness Detection
02C,08/07/2024,14.00-16.30,Random	System identification of a flexible beam structure
02C,08/07/2024,14.00-16.30,Random	Image Captioning Device For The Blind
02D,08/07/2024,08.00-10.30,Random	Development of Tactile Software for Blind Student
02D,08/07/2024,08.00-10.30,Random	Reducing emissions by using special air filters for Coal-fired Power Plant
02D,08/07/2024,08.00-10.30,Random	Development of Dielectric Excavator Coupling
02D,08/07/2024,08.00-10.30,Random	Development of untouched coupling rotation system
02D,08/07/2024,08.00-10.30,Random	3. Eco-Friendly Chlorine Vapor Management: A Systematic Approach for Filtration and Water Reuse
02E,08/07/2024,10.30-13.00,Random	An Improvement puncher braille technology device.
02E,08/07/2024,10.30-13.00,Random	Development of magnet bearing rotation system
02E,08/07/2024,10.30-13.00,Random	Development of learning-based robot arm manipulation for charging of Autonomous Electric Vehicle (AEV)
02E,08/07/2024,10.30-13.00,Random	Force Control of Robot's End-Effector for Peg-in-Hole Task
02F,08/07/2024,14.00-16.30,Random	WEB - ENABLED IN SITU WATER QUALITY MONITORING SYSTEM
02F,08/07/2024,14.00-16.30,Random	Development of a Digital Twin Simulation for an Autonomous Surface Vessel
02F,08/07/2024,14.00-16.30,Random	Design and development of robotic marine for water quality monitoring
02F,08/07/2024,14.00-16.30,Random	Design and development of 4-DOF robotic arm for robot-assisted EV Charging station
02F,08/07/2024,14.00-16.30,Random	Development of automatic fault detection for water quality monitoring system
02G,09/07/2024,08.00-10.30,Random	Development of Noise Isolating Ear Insert for Cartilage Conduction Hearing Protection Device
02G,09/07/2024,08.00-10.30,Random	Development of PID-Flight Controller of A F450 Quadcopter
02G,09/07/2024,08.00-10.30,Random	Path Planning of Quadcopter through Robot Operating System (ROS)

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02G,09/07/2024,08.00-10.30,Random	water filling system with sound pitch
02G,09/07/2024,08.00-10.30,Random	Inverse Kinematic Planning of 6-DOF Manipulator Using Robot Operating System (ROS)
02G,09/07/2024,08.00-10.30,Random	Mathematical Modelling of A Quadcopter Flight Controller